

F08GGF (SOPMTR/DOPMTR) – NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

F08GGF (SOPMTR/DOPMTR) multiplies an arbitrary real matrix C by the real orthogonal matrix Q which was determined by F08GEF (SSPTRD/DSPTRD) when reducing a real symmetric matrix to tridiagonal form.

2 Specification

```

SUBROUTINE F08GGF(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,
1              INFO)
ENTRY      sopmtr(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,
1              INFO)
INTEGER    M, N, LDC, INFO
real     AP(*), TAU(*), C(LDC,*), WORK(*)
CHARACTER*1 SIDE, UPLO, TRANS

```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine is intended to be used after a call to F08GEF (SSPTRD/DSPTRD), which reduces a real symmetric matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation: $A = QTQ^T$. F08GEF represents the orthogonal matrix Q as a product of elementary reflectors.

This routine may be used to form one of the matrix products

$$QC, Q^T C, CQ \text{ or } CQ^T,$$

overwriting the result on C (which may be any real rectangular matrix).

A common application of this routine is to transform a matrix Z of eigenvectors of T to the matrix QZ of eigenvectors of A .

4 References

- [1] Golub G H and van Loan C F (1996) *Matrix Computations* Johns Hopkins University Press (3rd Edition), Baltimore

5 Parameters

1: SIDE — CHARACTER*1 *Input*

On entry: indicates how Q or Q^T is to be applied to C as follows:

if SIDE = 'L', then Q or Q^T is applied to C from the left;

if SIDE = 'R', then Q or Q^T is applied to C from the right.

Constraint: SIDE = 'L' or 'R'.

2: UPLO — CHARACTER*1 *Input*

On entry: this **must** be the same parameter UPLO as supplied to F08GEF (SSPTRD/DSPTRD).

Constraint: UPLO = 'U' or 'L'.

- 3:** TRANS — CHARACTER*1 *Input*
On entry: indicates whether Q or Q^T is to be applied to C as follows:
 if TRANS = 'N', then Q is applied to C ;
 if TRANS = 'T', then Q^T is applied to C .
Constraint: TRANS = 'N' or 'T'.
- 4:** M — INTEGER *Input*
On entry: m , the number of rows of the matrix C ; m is also the order of Q if SIDE = 'L'.
Constraint: $M \geq 0$.
- 5:** N — INTEGER *Input*
On entry: n , the number of columns of the matrix C ; n is also the order of Q if SIDE = 'R'.
Constraint: $N \geq 0$.
- 6:** AP(*) — *real* array *Input*
Note: the dimension of the array AP must be at least $\max(1, M*(M+1)/2)$ if SIDE = 'L' and at least $\max(1, N*(N+1)/2)$ if SIDE = 'R'.
On entry: details of the vectors which define the elementary reflectors, as returned by F08GEF (SSPTRD/DSPTRD).
- 7:** TAU(*) — *real* array *Input*
Note: the dimension of the array TAU must be at least $\max(1, M-1)$ if SIDE = 'L' and at least $\max(1, N-1)$ if SIDE = 'R'.
On entry: further details of the elementary reflectors, as returned by F08GEF (SSPTRD/DSPTRD).
- 8:** C(LDC,*) — *real* array *Input/Output*
Note: the second dimension of the array C must be at least $\max(1, N)$.
On entry: the m by n matrix C .
On exit: C is overwritten by QC or $Q^T C$ or CQ^T or CQ as specified by SIDE and TRANS.
- 9:** LDC — INTEGER *Input*
On entry: the first dimension of the array C as declared in the (sub)program from which F08GGF (SOPMTR/DOPMTR) is called.
Constraint: $LDC \geq \max(1, M)$.
- 10:** WORK(*) — *real* array *Workspace*
Note: the dimension of the array WORK must be at least $\max(1, N)$ if SIDE = 'L' and at least $\max(1, M)$ if SIDE = 'R'.
- 11:** INFO — INTEGER *Output*
On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = $-i$, the i th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed result differs from the exact result by a matrix E such that

$$\|E\|_2 = O(\epsilon)\|C\|_2,$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of floating-point operations is approximately $2m^2n$ if `SIDE = 'L'` and $2mn^2$ if `SIDE = 'R'`.

The complex analogue of this routine is F08GUF (CUPMTR/ZUPMTR).

9 Example

To compute the two smallest eigenvalues, and the associated eigenvectors, of the matrix A , where

$$A = \begin{pmatrix} 2.07 & 3.87 & 4.20 & -1.15 \\ 3.87 & -0.21 & 1.87 & 0.63 \\ 4.20 & 1.87 & 1.15 & 2.06 \\ -1.15 & 0.63 & 2.06 & -1.81 \end{pmatrix},$$

using packed storage. Here A is symmetric and must first be reduced to tridiagonal form T by F08GEF (SSPTRD/DSPTRD). The program then calls F08JJF (SSTEBZ/DSTEBZ) to compute the requested eigenvalues and F08JKF (SSTEIN/DSTEIN) to compute the associated eigenvectors of T . Finally F08GGF (SOPMTR/DOPMTR) is called to transform the eigenvectors to those of A .

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```

*      F08GGF Example Program Text
*      Mark 16 Release. MAG Copyright 1992.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER       (NIN=5,NOUT=6)
      INTEGER          NMAX, LDZ
      PARAMETER       (NMAX=8,LDZ=NMAX)
      real            ZERO
      PARAMETER       (ZERO=0.0e0)
*      .. Local Scalars ..
      real            VL, VU
      INTEGER          I, IFAIL, INFO, J, M, N, NSPLIT
      CHARACTER       UPLO
*      .. Local Arrays ..
      real            AP(NMAX*(NMAX+1)/2), D(NMAX), E(NMAX), TAU(NMAX),
+                   W(NMAX), WORK(5*NMAX), Z(LDZ,NMAX)
      INTEGER          IBLOCK(NMAX), IFAILV(NMAX), ISPLIT(NMAX),
+                   IWORK(NMAX)
*      .. External Subroutines ..
      EXTERNAL        sopmtr, ssptrd, sstebz, sstein, X04CAF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F08GGF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N

```

```

      IF (N.LE.NMAX) THEN
*
*      Read A from data file
*
      READ (NIN,*) UPLO
      IF (UPLO.EQ.'U') THEN
        READ (NIN,*) ((AP(I+J*(J-1)/2),J=I,N),I=1,N)
      ELSE IF (UPLO.EQ.'L') THEN
        READ (NIN,*) ((AP(I+(2*N-J)*(J-1)/2),J=1,I),I=1,N)
      END IF
*
*      Reduce A to tridiagonal form T = (Q**T)*A*Q
*
      CALL ssptrd(UPLO,N,AP,D,E,TAU,INFO)
*
*      Calculate the two smallest eigenvalues of T (same as A)
*
      CALL sstebz('I','B',N,VL,VU,1,2,ZERO,D,E,M,NSPLIT,W,IBLOCK,
+          ISPLIT,WORK,IWORK,INFO)
*
      WRITE (NOUT,*)
      IF (INFO.GT.0) THEN
        WRITE (NOUT,*) 'Failure to converge.'
      ELSE
        WRITE (NOUT,*) 'Eigenvalues'
        WRITE (NOUT,99999) (W(I),I=1,M)
*
*      Calculate the eigenvectors of T, storing the result in Z
*
      CALL sstein(N,D,E,M,W,IBLOCK,ISPLIT,Z,LDZ,WORK,IWORK,IFAILV,
+          INFO)
*
      IF (INFO.GT.0) THEN
        WRITE (NOUT,*) 'Failure to converge.'
      ELSE
*
*      Calculate the eigenvectors of A = Q * (eigenvectors of T)
*
      CALL sopmtr('Left',UPLO,'No transpose',N,M,AP,TAU,Z,LDZ,
+          WORK,INFO)
*
*      Print eigenvectors
*
      WRITE (NOUT,*)
      IFAIL = 0
*
      CALL X04CAF('General',' ',N,M,Z,LDZ,'Eigenvectors',IFAIL)
*
      END IF
    END IF
  END IF
  STOP
*
99999 FORMAT (3X,(9F8.4))
END

```

9.2 Program Data

F08GGF Example Program Data

```
4                               :Value of N
'L'                             :Value of UPL0
2.07
3.87 -0.21
4.20  1.87  1.15
-1.15  0.63  2.06 -1.81 :End of matrix A
```

9.3 Program Results

F08GGF Example Program Results

Eigenvalues

```
-5.0034 -1.9987
```

Eigenvectors

```
          1          2
1  0.5658 -0.2328
2 -0.3478  0.7994
3 -0.4740 -0.4087
4  0.5781  0.3737
```
